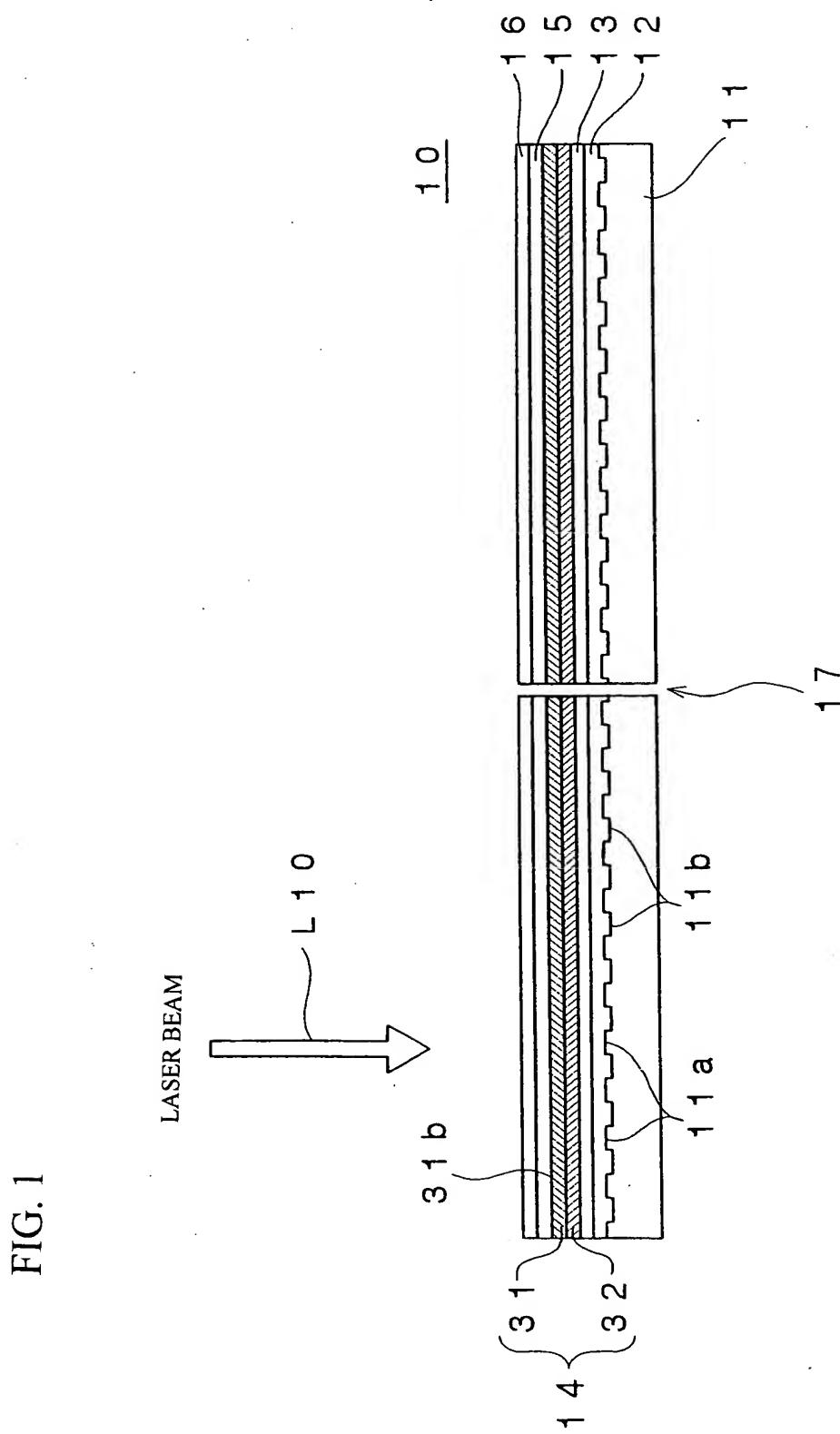
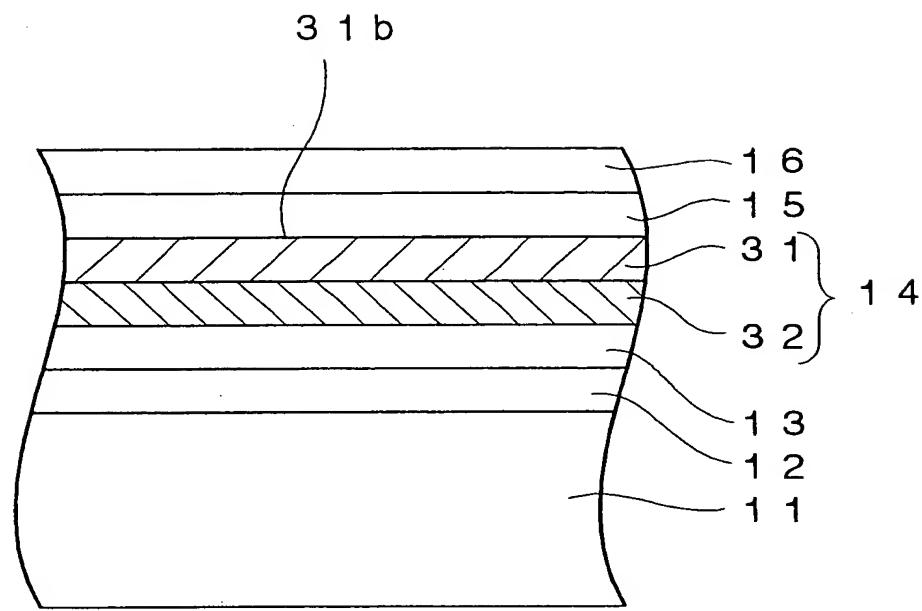


1 / 1 2

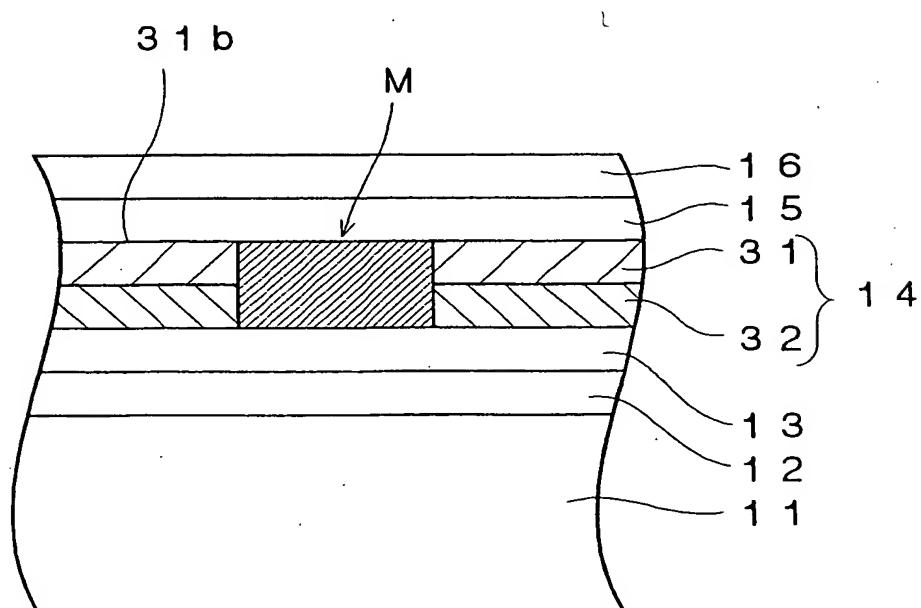


2 / 1 2

FIG. 2



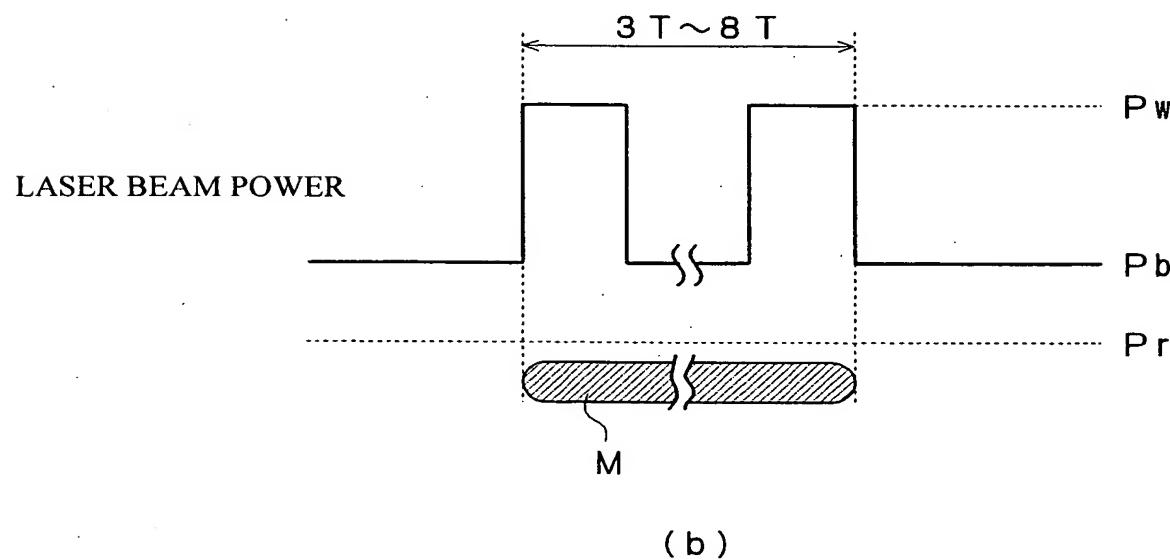
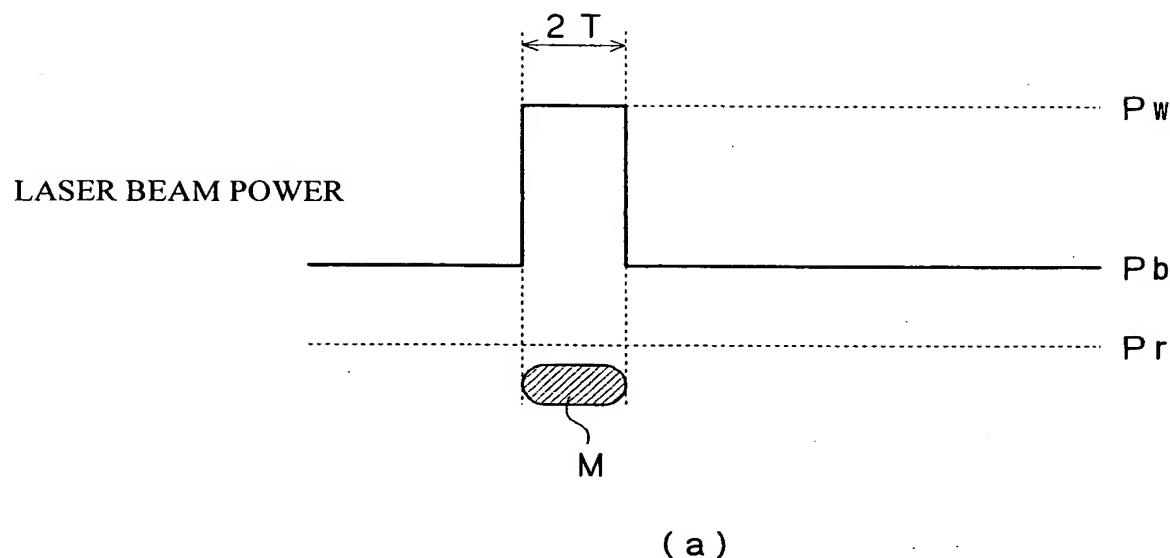
( a )



( b )

3 / 1 2

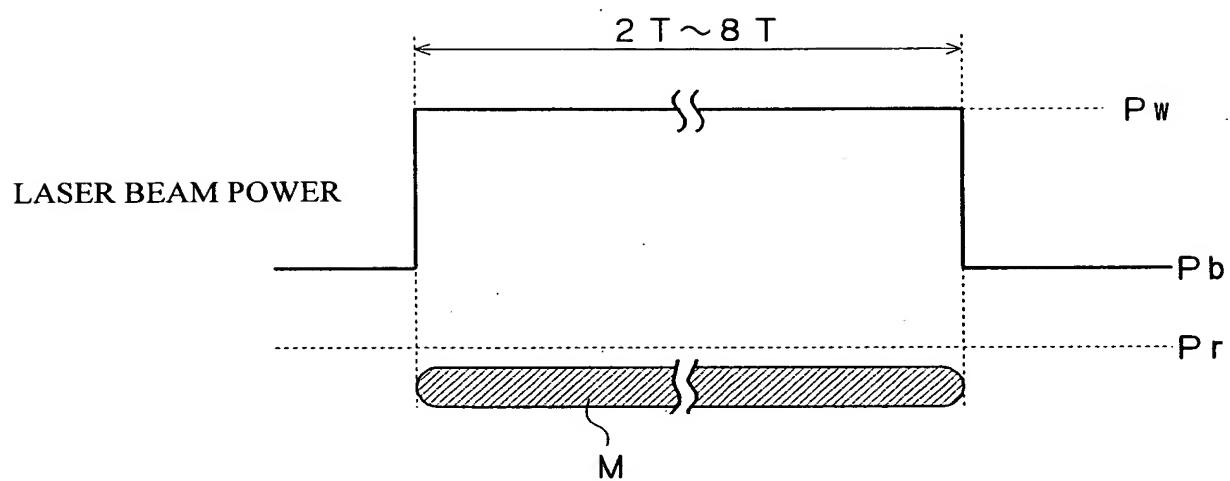
FIG. 3



10/516701

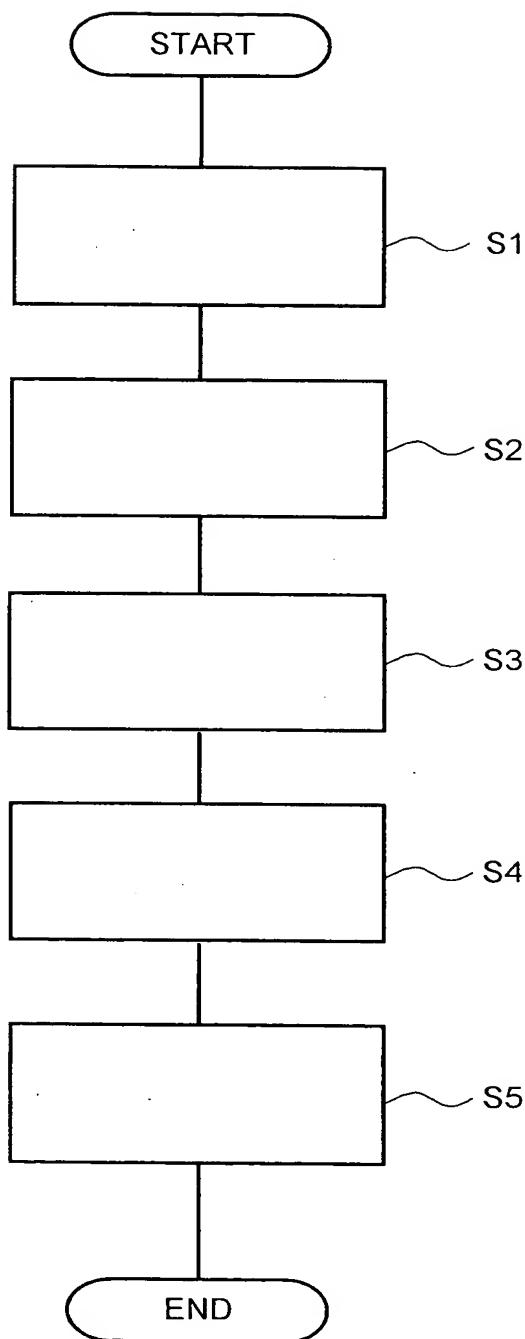
4 / 1 2

FIG. 4



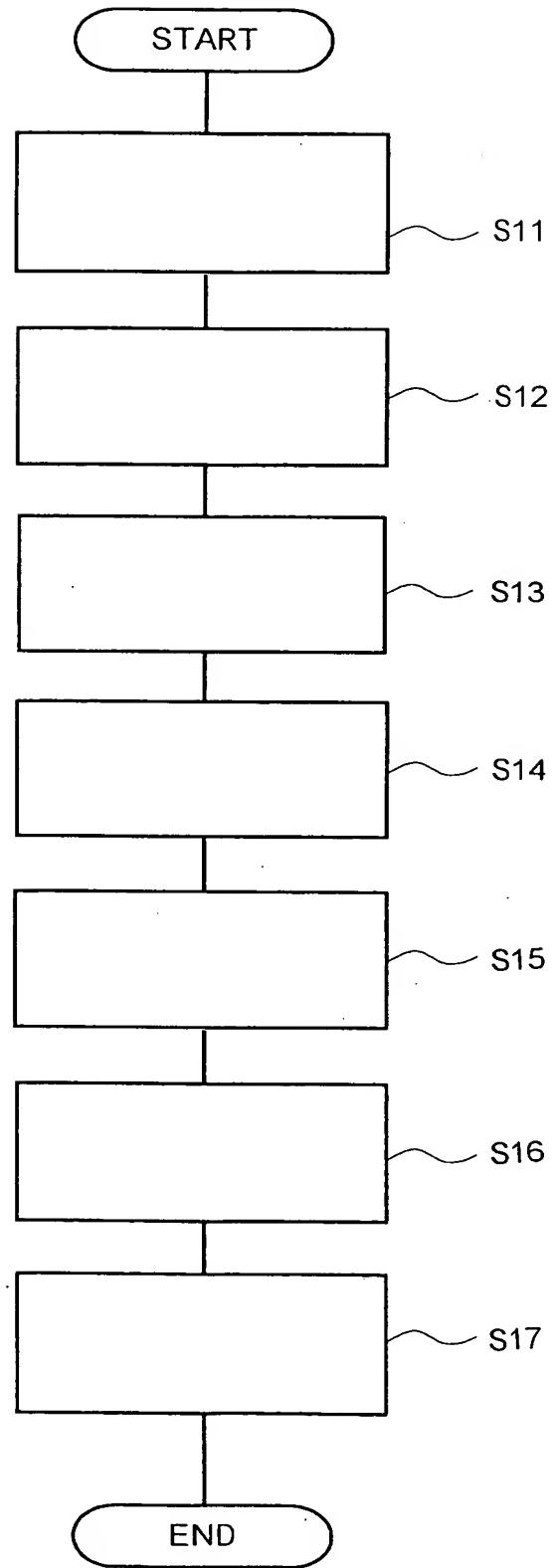
5 / 1 2

FIG. 5



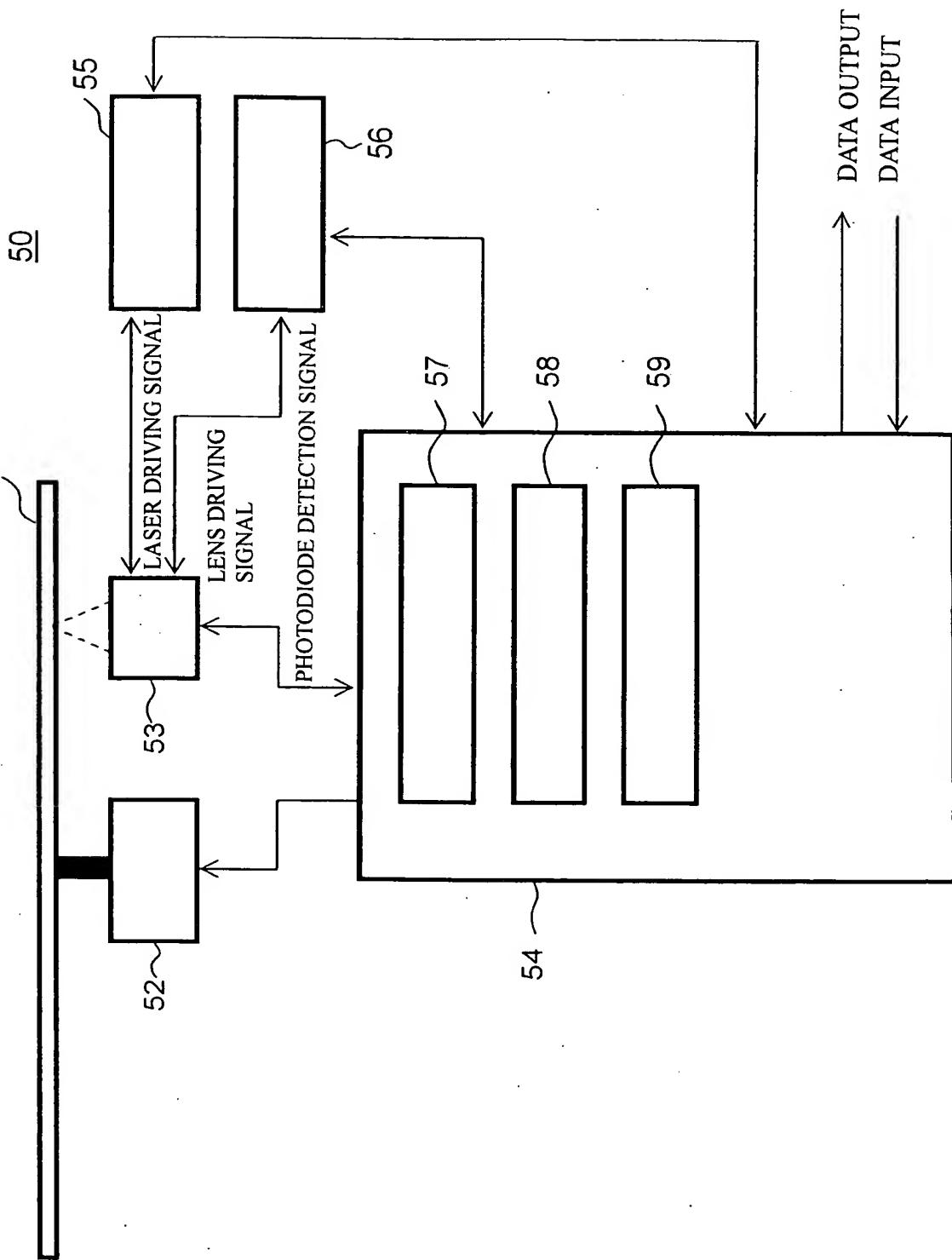
6 / 1 2

FIG. 6



7 / 1 2

FIG. 7



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FIG. 8

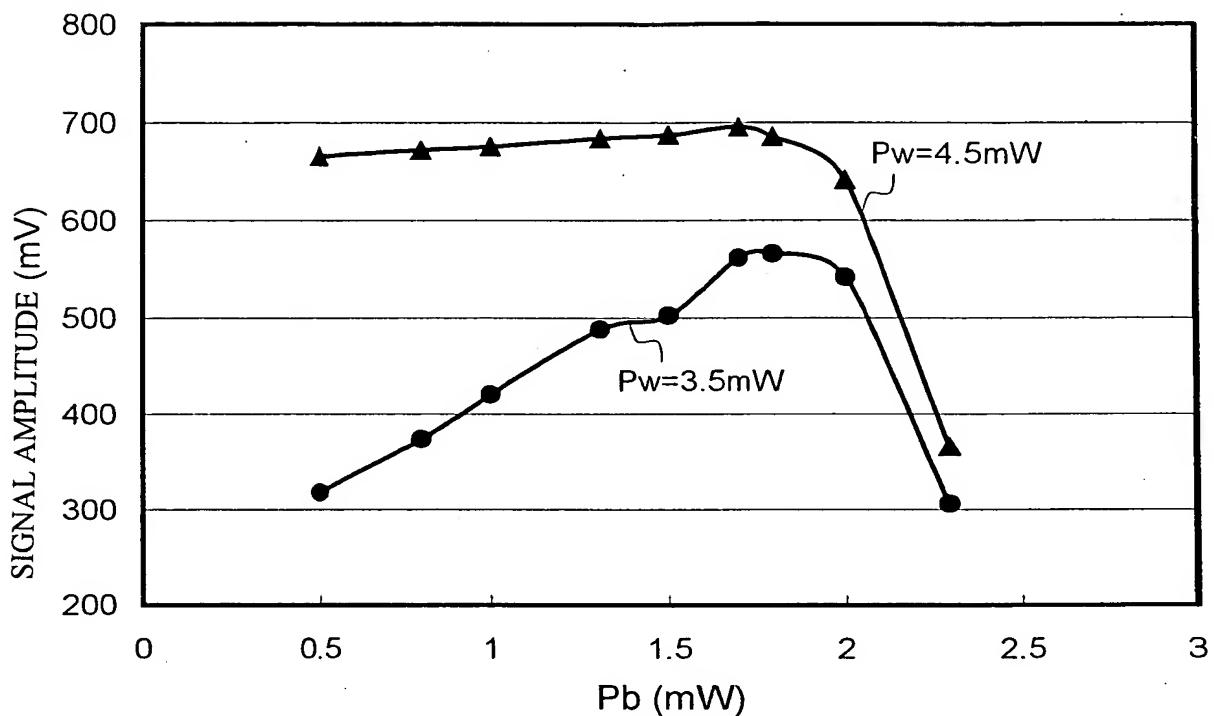
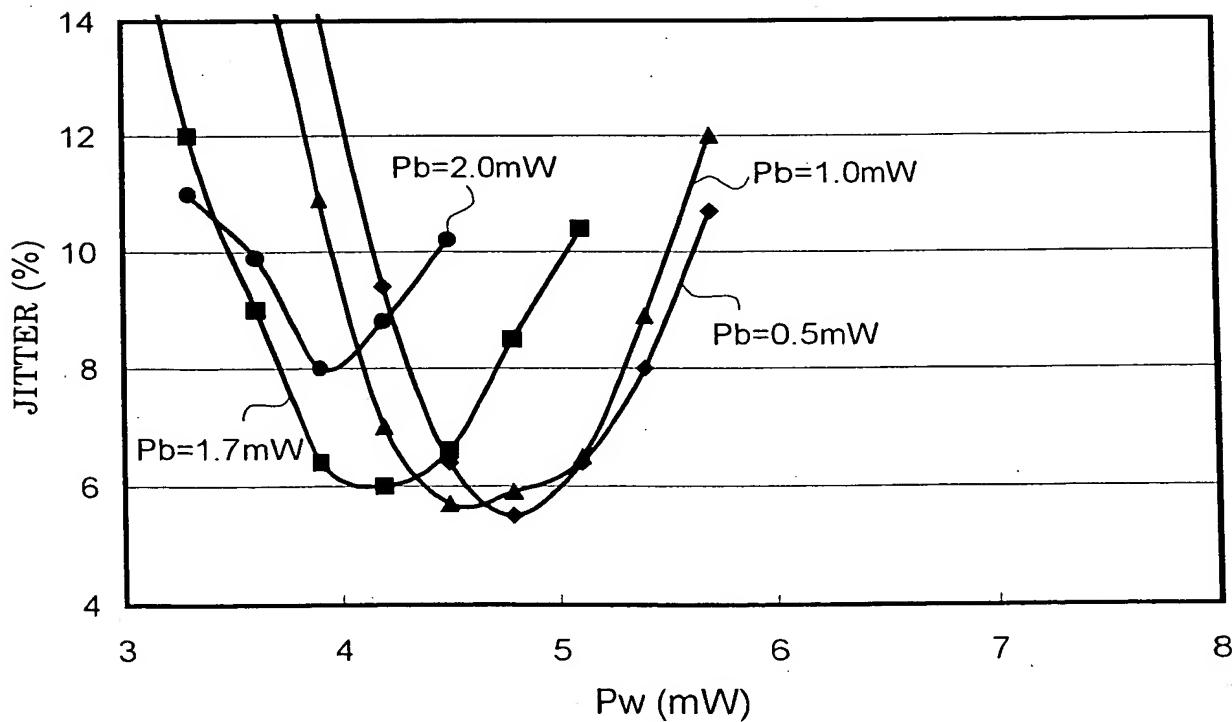


FIG. 9



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FIG. 10

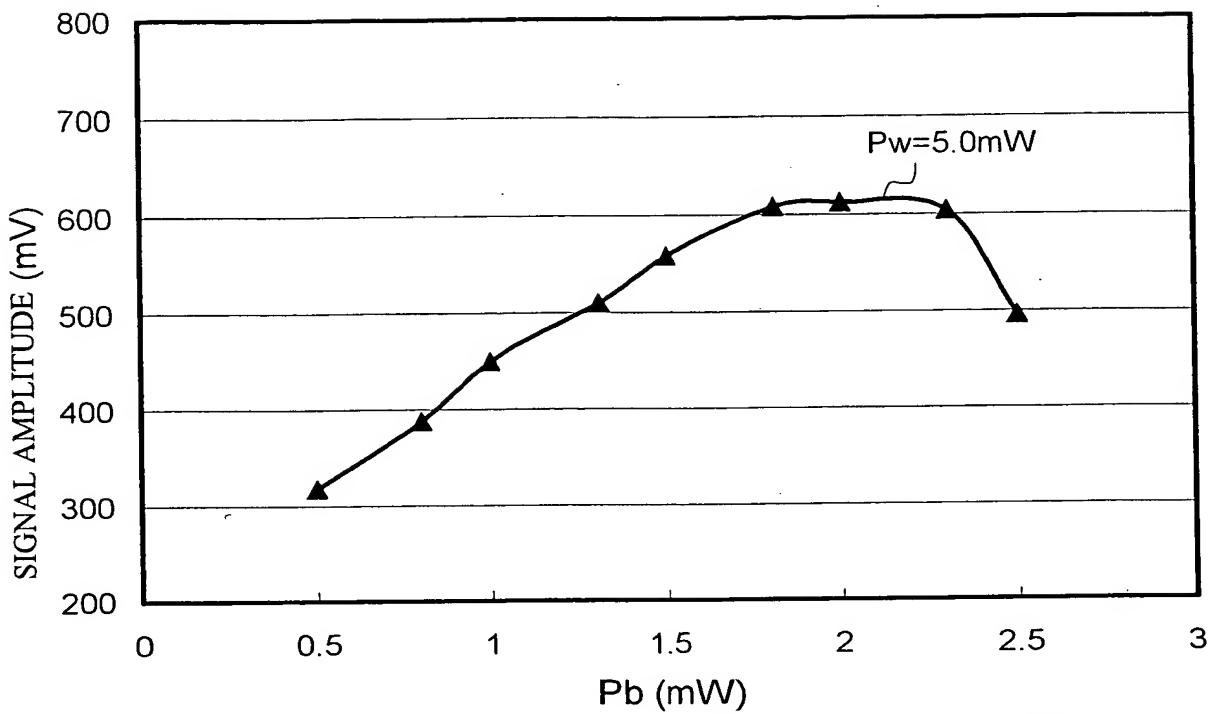
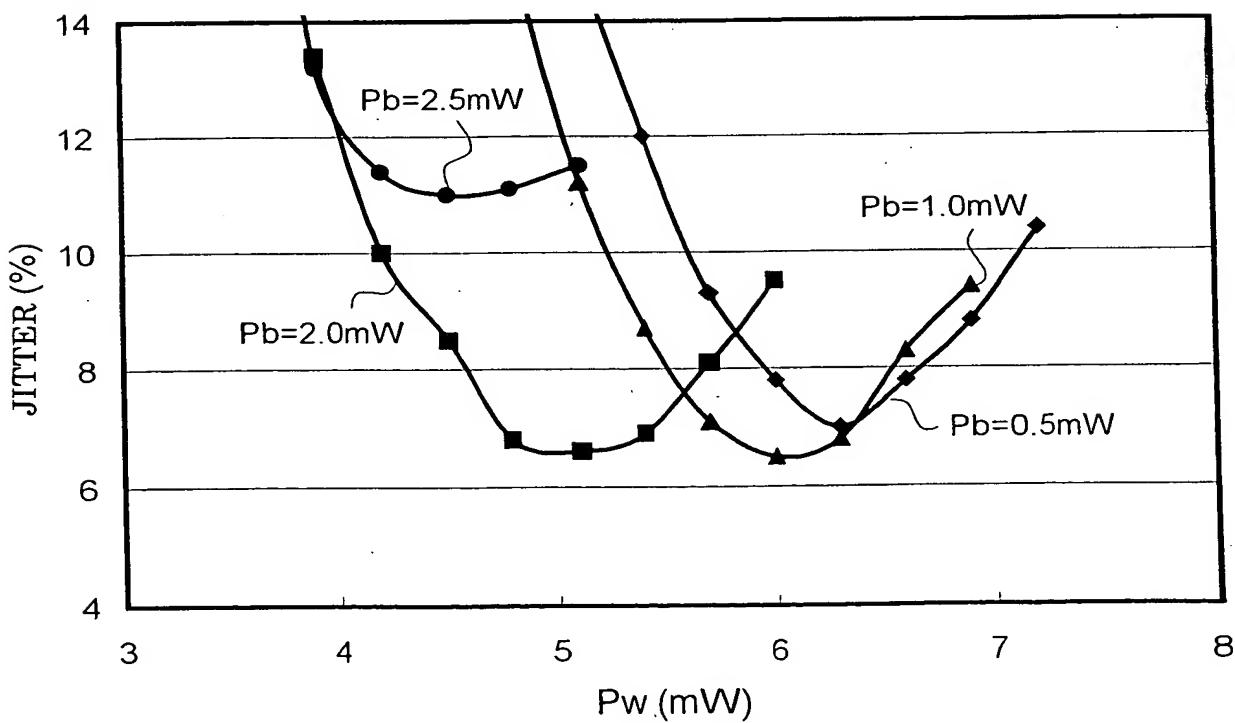


FIG. 11



1 0 / 1 2

FIG. 12

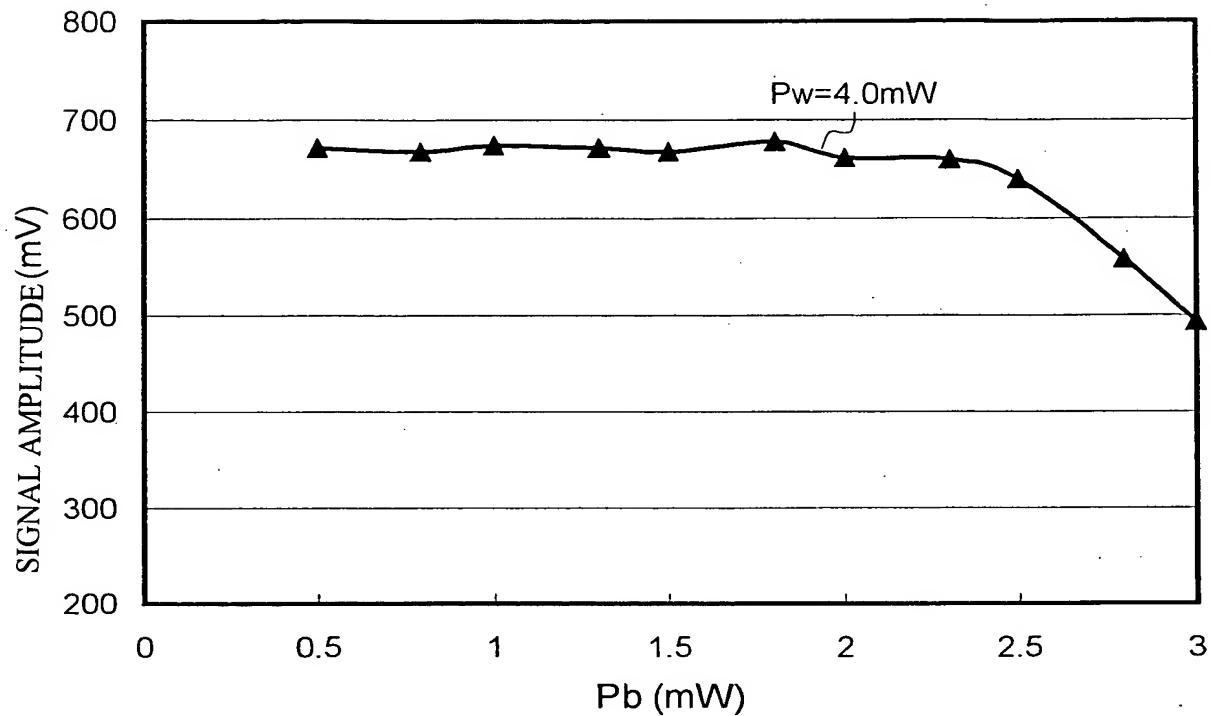
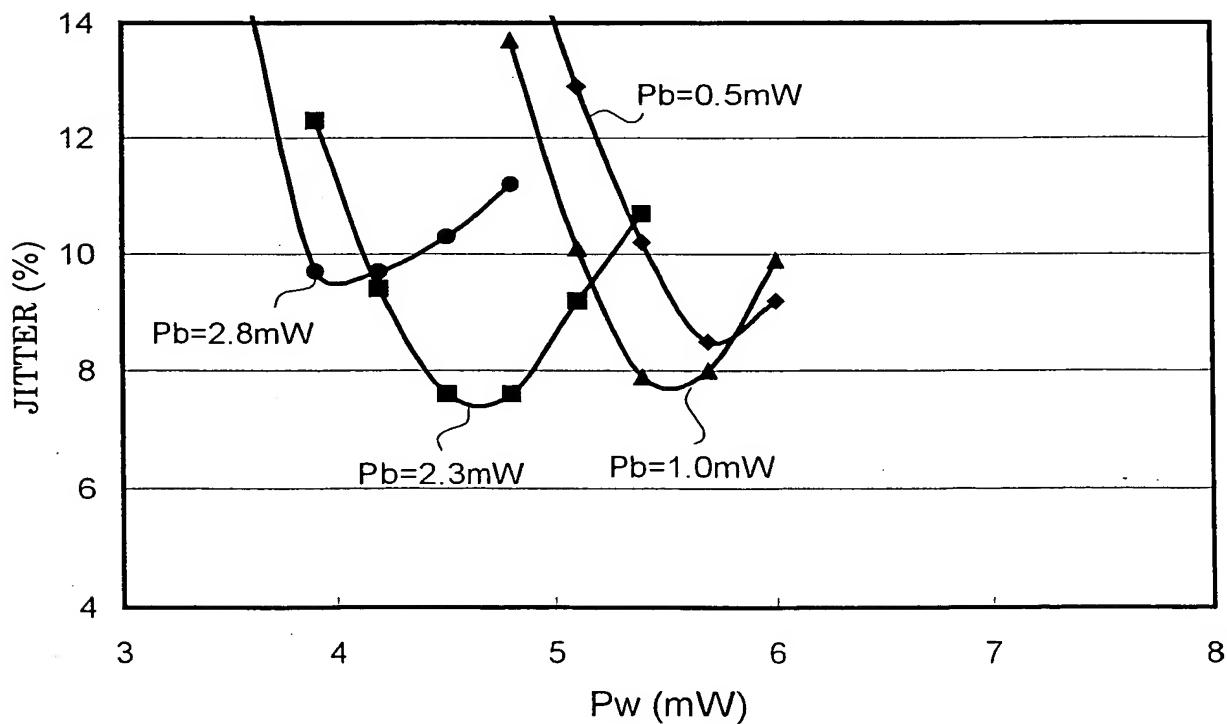


FIG. 13



1 1 / 1 2

FIG. 14

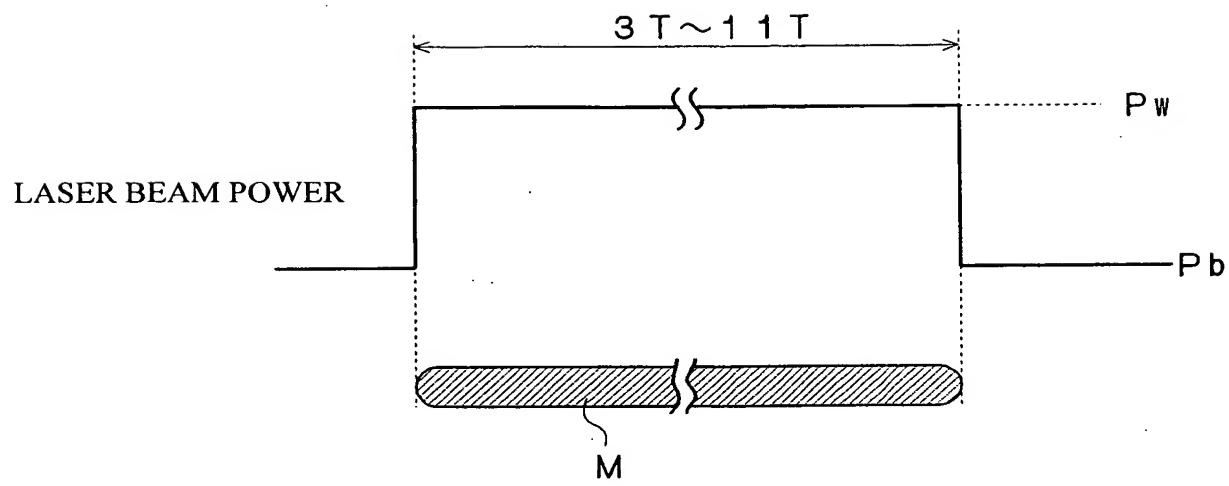
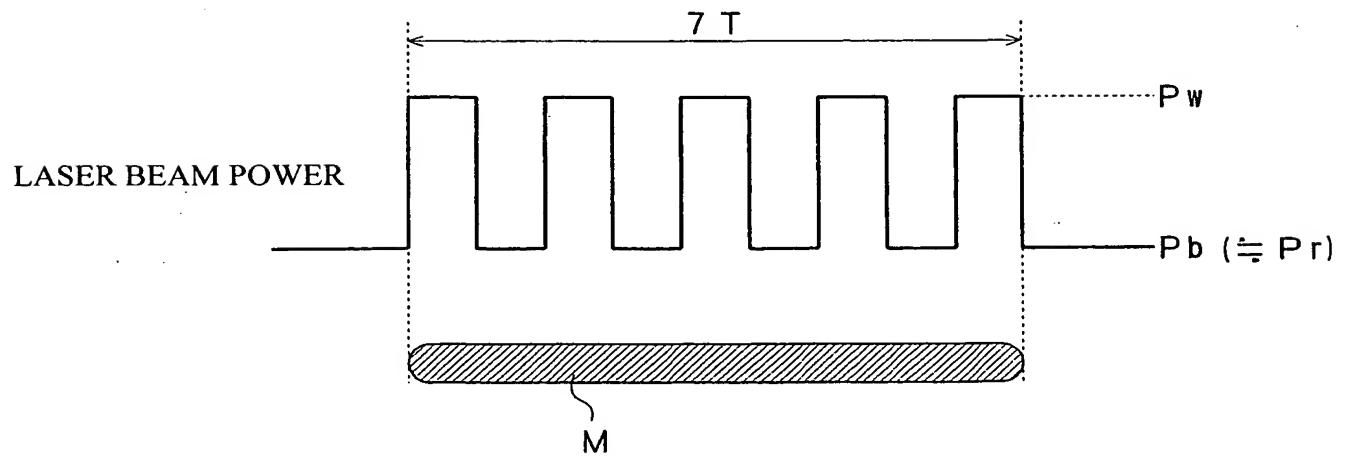


FIG. 15



1 2 / 1 2

5 2 ..... SPINDLE MOTOR  
5 3 ..... HEAD  
5 4 ..... CONTROLLER  
5 5 ..... LASER DRIVE CIRCUIT  
5 6 ..... LENS DRIVE CIRCUIT  
5 7 ..... FOCUS SERVO TRACKING CIRCUIT  
5 8 ..... TRACKING SERVO CIRCUIT  
5 9 ..... LASER CONTROL CIRCUIT  
S 1 ..... RECORDING FIRST TEST SIGNALS  
S 2 ..... DETERMINING AN OPTIMUM LEVEL *PB0* OF *PB*  
S 3 ..... RECORDING SECOND TEST SIGNALS  
S 4 ..... DETERMINING AN OPTIMUM LEVEL *PW0* OF *PW*  
S 5 ..... STORING *PB0* AND *PW0*  
S 1 1 ..... RECORDING SECOND TEST SIGNALS  
S 1 2 ..... TENTATIVELY DETERMINING AN OPTIMUM LEVEL *PW0* OF *PW*  
S 1 3 ..... RECORDING FIRST TEST SIGNALS  
S 1 4 ..... DETERMINING AN OPTIMUM LEVEL *PB0* OF *PB*  
S 1 5 ..... RECORDING SECOND TEST SIGNALS  
S 1 6 ..... DETERMINING AN OPTIMUM LEVEL *PW0* OF *PW*  
S 1 7 ..... STORING *PB0* AND *PW0*